

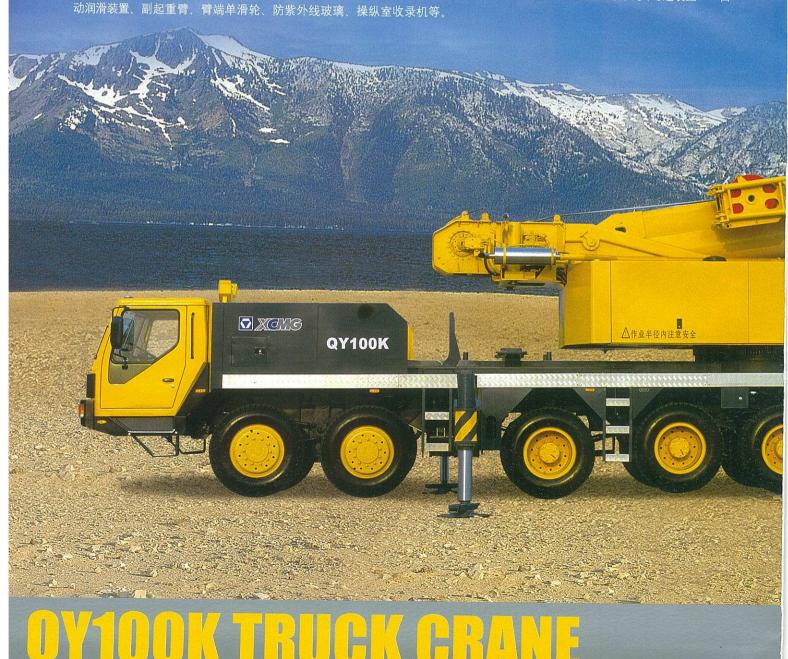
QY100K领先型一百吨级产品的新纪元

QY100K Leading Class-New Era for Hundred-Ton Truck Cranes

早在2003年初,徐州重型机械有限公司就推出了百吨级汽车起重机。

今天,采用PROE设计手段,经过多种可靠性模拟实验,在各种精密大型设备锻造下,QY100 K立在国内**百吨级产品** 的最高端。

- 零差错制造:一直以来,制造系统无法精确执行技术人员的设计思想,需要经历反复的修改和调整,如今,徐重的100 K 在 投产之前,运用电脑模拟预装配技术,精确到每一个制造工艺流程,确保了产品更高效能的表现。
- 高智能: PLC计算机集成控制系统——所有起重机的重要电子元件的电子信号经过计算机集中处理,使起重机的所有操作更加 简单方便,全面提高起重机的作业安全性、可靠性和作业效率。
- 高节能: 恒功率变量系统——与集成式控制器相结合,可根据负载变化自动调整系统输出流量和压力,速度控制精确灵敏。
- ➡ 持久: 强劲的工程机械专用发动机──上车配置进口沃尔沃发动机,确保产品在各种载荷状态均匀有力,可长时间、连续、 平稳作业:下车配置进口康明斯发动机,动力持久。
- 高效: 六桥越野起重机底盘──三桥驱动,驱动力强;三桥转向,转向灵活,通过性好,能迅速到达吊装位置。
- 高性能: 椭圆形截面的五节主吊臂──截面优化、吊臂重量减轻,起重能力得以完全释放。
 更便捷: 大弧面全视野整体式操纵室──可向上调节20°;自装卸平衡重──灵活组合平衡重,满足各种工况要求,可选装置──自



Courtesy of Crane. Market

FOR HUNDRED TON TRUCK CRANES



多平衡重组合-全面增强中长臂、大幅度起重能力

IMPROVES Mid-extended Boom Strength and Increases Lifting Capacity

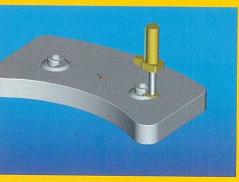


平衡重可遥控装卸

Remote control of counterweight



平衡重尾部为弧形结构,尽可能缩小了回转作业空间 Curved counterweight tail reduces swing radius



平衡重自装卸 Self-assembly of counterweight

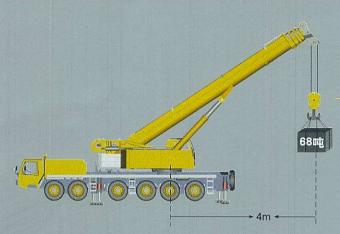
CRANE



平衡重遥控器 counterweight remote controller

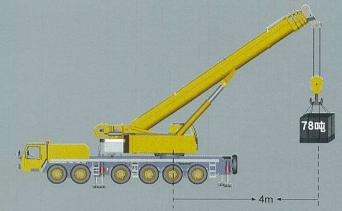
COMBINED COUNTERWEIGHT





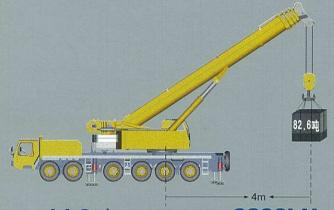
不挂平衡重最大力矩: 2734kN.m

Max, load moment without counterweight



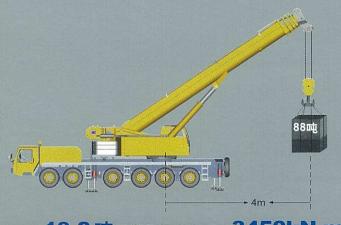
8.3 吨平衡重最大力矩: 3058kN.m

Max, load moment with 8.3t counterweight



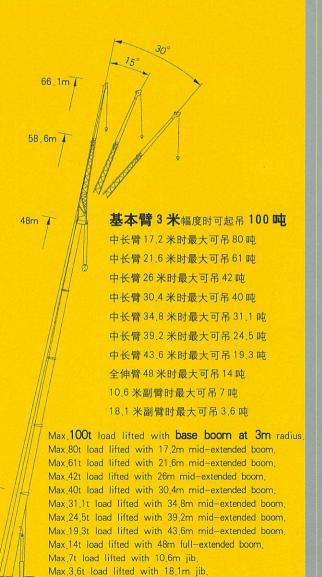
14.3 吨平衡重最大力矩: 3238kN.m

Max. load moment with 14.3t counterweight



19.2 吨平衡重最大力矩: 3450kN.m

Max. load moment with 19.2t counterweight



12.8m

00-0-000



精确、可靠的控制执行系统-PLC计算机集成控制系统、液压系统

ACCURATE AND RELIABLE SYSTEM FOR CONTROL AND EXECUTION

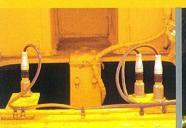
— PLC COMPLIES INTEGRATED SYSTEM AND HYDRALLIC SYSTEM



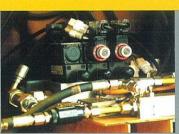
PLC计算机集成控制系统:

起重作业部分采用工程机械专用PLC可编程集成式控制器,控制信号和操纵特性曲线可实现数字化设定和调整。该控制器与变量液压系统相结合,能够更精准地根据负载变化自动调整系统输出流量和压力,操纵精确平稳。

- ◆免维护
- ◆进口电子元件
- ◆实时监测功能
- ◆故障诊断功能
- ◆方便准确的设定操纵特性



转台对中装置 turntable aligning device



卡套接头 ferrule-type pipe joint

液压系统 Hydraulic System

- ◆进口卡套式接头、零泄露、防污染
- ◆强效的液压油冷却系统
- ◆节能高效的变量起升液压系统 (专利号: 01237657.4)
- ◆防冲击自动找正的回转液压系统(专利号: 03219267.3)
- ◆性能卓越、运动可靠的进口泵、马达、阀类、密封等执行元件
- ◆高度集成的模块化阀组,管路简单,液阻小(专利号: 012044458.8)
- ♦ Imported ferrule—type pipe joints, free of leakage and antipollution
- ◆Effective hydraulic oil cooling system
- Variable hydraulic system of cost energy and high efficiency for hoist (Patent No.: 01237657.4)
- ♦ Hydraulic system of shockproof self-alignment for swing(Patent No.:03219267.3)
- Imported pump, motor, valves and sealing with excellent performance and reliability
- ♦ Integrated modular valve block with simple pipeline and less hydraulic resistance (Patent No.: 012044458.8)

卓越部件综合展示

PARTS WITH HIGH QUALITY AND EXCELLENT PERFORMANCE

OYIOOK

多边形高性能吊臂

Polygonal profile boom with excellent performance

◆ 截面优化显著地提高起重性能

Optimized cross-section remarkably improves lifting capacitty 性能提高率

performance improved rate (%)

16 -14 -12 -10 -8 -6 -4 -2 -

"U"形 U-shaped

1 2 边形 Twelve-side-shaped

8 边形 Octagonal

6 边形 Hexagonal



不同截面形状的起重性能对比

Lifting performance comparison among various boom profiles



吊臂对中装置 Boom aligning device



U型臂滑块 Slide pads for U-shaped boom

椭圆形截面的五节主吊臂

- ◆ QY100K 拥有国际最先进的椭圆形截面吊臂
- ◆吊臂选用进口超强钢
- ◆特殊的滑块和对中装置,使吊臂伸缩平稳,对中可靠
- ◆截面优化显著地提高起重性能

5 Boom Sections with Ovoid Boom Profile

- ♦ Most advanced ovoid boom profile
- ◆ Imported high strength steel
- Special slide pads and aligning devices make boom telescope smoothly and align accurately
- ♦ Optimized cross-section remarkably improves lifting capacity

起重臂伸缩系统

- ◆双缸加绳排伸缩方式,臂长从12.8米到48米,仅需160秒
- ◆多芯管伸缩油缸,双缸内部沟通,免除了软管卷筒
- ◆每节伸缩臂可从侧面得到充分的润滑
- ◆进口绳排和轴承

Boom Telescoping System

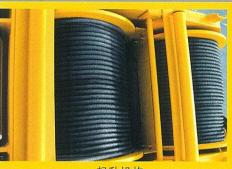
- Double-cylinder plus wire ropes for telescoping, boom extension from 12.8m to 48m only in 160 seconds
- Telescoping cylinder with multi-core pipes, double cylinder of internal connection free of hose reel
- Sufficient side lubrication for each boom section
- ♦ Imported wire ropes and bearings



多芯管伸缩油缸 Telescoping cylinder with multi-core pipes



每节伸缩臂可从侧面得到充分的润滑 Sufficient side lubrication for each boom section



起升机构 winches

起吊机构

- ◆选用臂端滑轮时,重物起吊40米只需30秒
- ◆采用常闭式行星减速机构
- ◆进口防旋转起升钢丝绳
- ◆ 0-80° 变幅时间只需 75 秒
- ◆每分钟2圈的回转速度
- ◆双独立起升机构



PAT收线器 PAT cord reel

Hoist

- ♦ With single sheave on boom tip, lift load up to 40m only in 30 seconds.
- Constant closed planetary gear reducer
- Imported anti-rotation winch ropes.
- ◆ Elevating from 0° to 80° only in 75 seconds.
- Swing speed 2 rpm.
- Two independent winches.



TRUCK CRANE



上车沃尔沃发动机 Volvo engine on crane superstructure

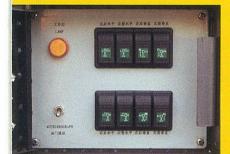


下车康明斯发动机 Cummins engine on crane chassis

动力系统

- ◆上车配备输出功率为174KW的沃尔沃工程机械专用全新涡轮 增压柴油机, 耗油量小、扭矩大
- ◆下车配备输出功率为324KW的康明斯欧 | 电喷最新型发动机
- ◆通过程序监控的柴富变速箱
- ◆传动系统强劲可靠

- ◆ Equipped with Volvo turbocharged diesel engine on crane superstructure. output 174kW, less fuel consumption and powerful torque.
- Powerful Cummins engine on crane chassis, electronic injection,output 324kW, Euro II
- ♦ ZF transmission monitored by program
- Powerful drive train.



支腿操纵

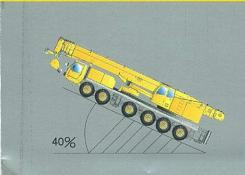
- ◆电控操纵,并设有油门增速按钮
- ◆全伸支腿时, 无需第5支腿, 可实现360°全回转作业
- ◆双侧均配有夜视水平仪(专利号: 03219322,X)
- ◆各支腿可独立操作,亦可同时操作
- ◆双H型支腿,水平支腿最大横向跨距7.6米,纵向跨距7.56米

Operating Outriggers

- Electric control with accelemtion button.
- ◆ Without 5th outrigger, 360° swing on fully-extended outriggers.
 ◆ Night visual level gauge on both sides (Patent No.:03219322.X)
- Each outrigger operated either independently or simultaneously.
- ◆ Double H-shaped outrigger with max. span 7.6m(transverse) and 7.56m (longitudinal)



可实现 360° 全回转作业 Operation of 360° full swing





底盘转向

- ◆三桥驱动,三桥转向
- ◆最小转弯直径24米
- ◆最大爬坡度40%

Steering

- ◆ 3-axle drive and 3-axle steering
- Min, turning diameter 24m
- ◆ Max. grade-ability 40%

人性化的体贴设计

ERGONOMIC AND CONSIDERATE DESIGN

舒适的工程机械专用驾驶室

- ◆设计合理的内装饰, 良好的 隔音效果
- ◆可调式驾驶员减震座椅
- ◆可调式方向盘
- ◆电控自动升降玻璃
- ◆可自动除霜
- ◆内设 CD 机

Comfortable driver's cab for construction machinery

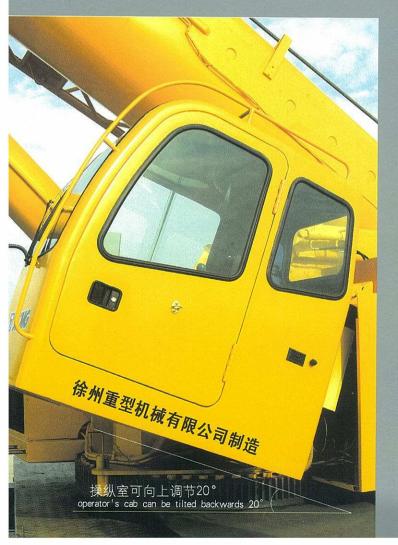
- ◆ Reasonable internal decoration, good isolation
- Adjustable damping seat for driver
- Adjustable steering wheel
- · Electrical side window glass lifter
- Automatic defrosting
- ◆CD player

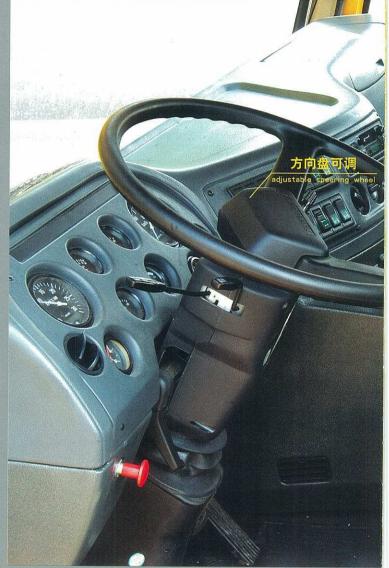
新型的操纵室

- ◆流线型整体复合材料壳体
- ◆大圆弧整体式前视窗,清除 视觉死角
- ◆可调式操作员座椅
- ◆先导手柄轻轻一推,各项作业 ◆Complete operation by gentle touch 轻松完成

New Operator's Cabin

- Integrated streamline boby made of
- Integrated front window and roof window, free of dead space of view
- Adjustable seat for operator
- of the pilot handle

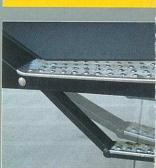






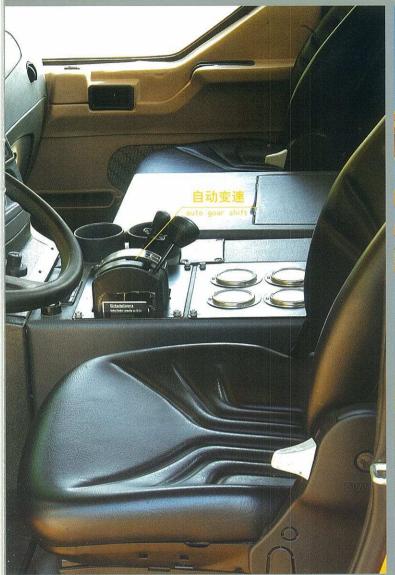
自动润滑装置 centralized lubrication





脚踏板(遇障碍可自动收起) step plate (auto stowing by encountering obstacle)
Courtesy of Crane.Market







GO LAND CAREFULL DESIGN





操纵室内的收放音机 radio-cassette recorder in operator's cab





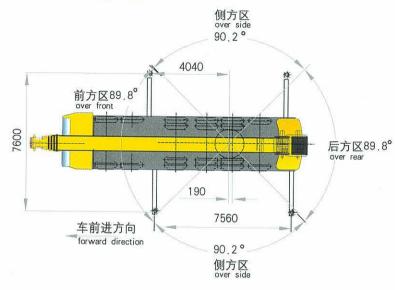


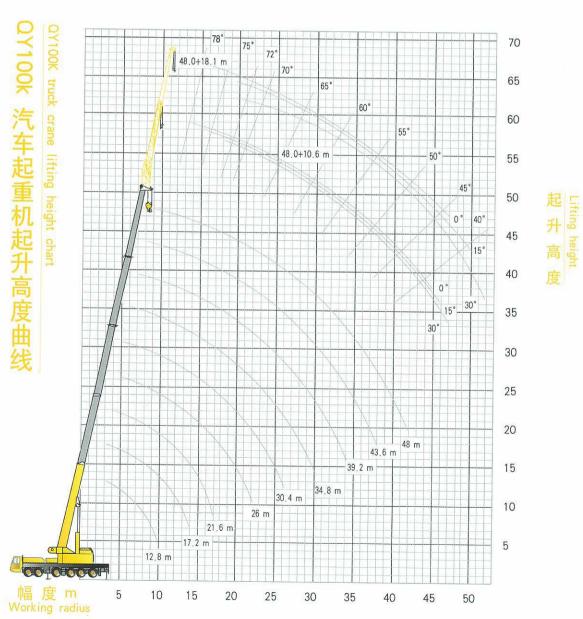
座椅(可调整) seat(adjustable)

QY100K汽车起重机技术参数

QY100k 汽车起重机作业区域划分

QY100K Truck Crane Working Area



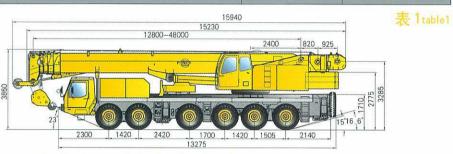


QY100K TRUCK CRANE TECHNICAL SPECIFICATION

起重机行驶状态主要技术参数表

Main Technical Data in Travel State

类别 Category		项目 Item	单位 Unit	参数 Parameters
尺寸参数	整机(长×宽	×高) Overall (Length × Width × Height)	mm	15230 × 3000 × 3860
Outline Dimensions	轴距 Wheel	space	mm	1420+2420+1700+1420+1505
	行驶状态总质	量 Dead weight in travel state	kg	58000
		1轴 1st axle	kg	7500
重 量		2轴 2nd axle	kg	7500
参 数	轴荷	3轴 3rd axle	kg	10000
Weight	数 轴荷 3轴 3rd axle Axle load 4轴 4th axle 5轴 5th axle 6轴 6th axle 发动机额定功率 Engine rated output 发动机额定扭矩 Engine rated torque 发动机额定转速 Engine rated speed	4轴 4th axle	kg	12500
	5轴 5th axle 6轴 6th axle 发动机额定功率 Engine rated ou	5轴 5th axle	kg	12500
		6轴 6th axle	kg	8000
カ カ ー	发动机额定功	率 Engine rated output	kw/(r/min)	324/1800
	发动机额定扭	矩 Engine rated torque	N,m/(r/min)	2100/1200
多 蚁 Power	发动机额定转	速 Engine rated speed	r/min	1900
rower	最小离地间隙	Min.ground clearance	mm	310
	接近角 Appro	ach angle	.0	23
行 驶	离去角 Depart	ure angle	0	15
参 数	制动距离(车)	起为 30km/h) Braking distance(at 30km/h)	m	≤ 10
Travel	最大爬坡度 N	Max.grade ability	%	40
Performance	最小转弯直径	Min, turning diameter	m	24
	百公里油耗 F	uel consumption of 100km	L	70



起重机作业状态主要技术参数表

Main Technical Data for Lifting Operation

类别 Category		项目	Item		单位 Unit	参数 Parameters
	最大额定总起重量 Max	total rated lift	ing capacity		t	100
	最小额定幅度 Min,rated	working radiu	S		m	3
	转台尾部回转半径	平衡重处 A	t counterweight		mm	4200
	Turning radius at swing table tail	副卷处 At a	auxilary winch	mm	4590	
		基本臂 Base	boom		kN,m	3450 (4m × 88t)
主 要	最大起重力矩 Max,load	最长主臂 Fu	III-extend boom	kN,m	1670(24m × 7.1t)	
性能		最长主臂+副]臂 Full-exten	d boom+Jib	kN.m	1127(19,2m × 6t)
参 数	+ pa pr == (\(\lambda \) (\(\lambda \) (\(\lambda \)	纵向 Longitu	ıdinal distance		m	7.56
Lifting performance	支腿距离(全伸)Outrigger span	横向 Lateral	distance		m	7.6
Partie Manager		基本臂 Base	boom		m	12,8
	起升高度 Lifting height	最长主臂 Fu	ill-extend boom		m	47.9
	50 W. 1700 W. A. W. S. W	最长主臂+副	臂 Full-extend	boom+Jib	m	65,9
		基本臂 Base	boom		m	12.8
	起重臂长度 Boom length	最长主臂 Fu	III-extend boom	m	48	
		最长主臂+畐]臂 Full-extend	m	48+18.1	
	副臂安装角 Jib offset	0	0, 15, 30			
	起重臂变幅时间 Boom ele	evating time	起臂 Boor	m raising	S	75
工作	起重臂伸缩时间 Boom te	lescoping time	全伸 Full-	extending	s	160
速度	最大回转速度 Max.swin	g speed			r/min	2
参数 Working	支腿伸缩时间		水平支腿 Outrigger beam	同时伸/缩 Extending/Retracting	s	25/15
speed	Outrigger extending and reti	racting time	垂直支腿 Outrigger jack	同时伸/缩 Extending/Retracting	s	45/25
	起升速度(单绳、第	四层)	主起升机构 N	Main winch	m/min	105
	Hoist speed(single line at		副起升机构	Aux, winch	m/min	104

表 2table2

QY100K汽车起重机技术参数

QY100K 汽车起重机主臂起重性能表

QY100K Truck Crane Total Rated Lifting Load for Boom

7710819 NOTE (2011)	11/1/2001	
单位:	n:t:	Unit-t
77.11	ич.	OUILLE

Wit		不挂平 unterwe	·衡重 ight,360	全伸 。 swin	支腿 30 g on fu	60°作 II-exten	ded out	riggers	
幅 度 Working			主臂	长度(m) boon	n length			
radius (m)	12.8	17.2	21.6	26	30,4	34.8	39.2	43.6	48
3	93	78					100		
4	68	70	60						
5	55	55	52.3	42	40	Bell	100	FRY S	1
6	45	44	42	42	36.5	31.1			
7	36,5	35	36	36	33.5	29	24.5		
8	28.3	27.8	27.5	29,4	30.7	27.2	23,3	19.3	
9	20.7	20,3	20	21.7	22,9	23.8	21.8	18.4	14
10	15.7	15.4	15.1	16.7	17.7	18.5	19	17,5	13,4
12		9,3	9.1	10,5	11.4	12.1	12.6	13.1	11,6
14		5.7	5.5	6.8	7.7	8.3	8.8	9.2	9.5
16			3.2	4.4	5.2	5.8	6.4	6.6	7
18			1.4	2.6	3.4	4	4.6	4.8	5,1
20				1,3	2.1	2.7	3.3	3,5	3.7
22					1.1	1.6	2.2	2.4	2.7
24					123		1.4	1.6	1.8
26									1,1
倍率 Parts of line	12	10	8	6	5	4	4	3	2
最小主臂仰角 (°) Min,boom angle	20	22	23	34	40	49	52	57	58
最大主臂仰角 (°) Max.boom angle	71	77	77	78	80	81	81	81	81
使用吊钩 hook block		中吊钩(10 k block for					沟(418kg ck for 50t)	

表 3-1table3-1

							单	位: 吨	Unit:
	1 24		平衡重						
幅度	4,31 COL	interwei	ght,360° 土程等。	swing 长度(m)		extend	ed outri	ggers	
幅度 Working radius(m)	12.8	17.2	21.6	26	30.4	34 8	39.2	43 6	48
3	100	80	21.0	20	30,4	34.0	35,2	43.0	40
4	82.6	70	61						
5	65.8	61	54.3	42	40				0.000
6	54 9	54	48 7	42	36 5	31.1			
7	45	45	44 1	38.6	33,5	29	24 5		
8	38.5	38	37.8	35 3	31 1	27 2	23,3	19 3	
9	33 5	33	33 32	32.3	28.7	25.4	21.8	18.4	14
10	28 5	29	28.5	29 9	26.6	23.6	20,6	17.5	13.4
12	The same	19.5	19.3	20.7	21.6	20.9	18.5	15.7	11 6
14		13.8	13.7	14.9	15.8	16 4	16.3	14.2	11.3
16		10.0	9.9	11.1	11.9	12.6	13.1	13	10.1
18			7.2	8.4	9 2	9.8	10.4	10.6	9.2
20		Division .		6.4	7.2	7.7	8.3	8.5	8 3
22				4.8	5.6	6.1	6.7	6.9	7.2
24		(Upper Tight	1002.11		4 3	4.9	5 4	5,6	5 9
26					3.3	3,8	4.4	4.6	4.8
28	No. of the last					3.0	3.5	3.7	3.9
30						2.2	2.8	2,9	3.2
32	19-19-1	HAVE			ast at	San San	2.2	2.3	2 6
34							1.6	1 7	2.0
36	NET 1		VIII I		1	TO STORE	A 2015	1,3	1.5
38									1,1
倍率	12	10	8	6	5	4	4	3	2
Parts of line 设小主臂仰角 (°) Min.boom angle	20	22	23	24	25	25	26	32	37
最大主臂仰角 (°) Max boom angle	71	77	77	78	80	81	81	81	81
使用吊钩 hook block		吊钩(10 block for 1				50 吨吊包 hook bloc			

表 3-2table3-2

单位: 吨 Unit:t

		101 to 100 to 100						型位: 阿	Uni	
						° 作业				
幅度	st count	erweigh				extende		gers		
Working		N PHE			舒长度(m) boom length					
radius (m)	12.8	17.2	21.6	26	30.4	34,8	39.2	43.6	48	
3	100	80								
4	78	70	61							
5	62	61	54.3	42	40					
6	51	50	48.7	42	36,5	31.1				
7	42.2	42	44.1	38.6	33.5	29	24.5			
8	35.8	35,8	38.3	35,3	31.1	27.2	23.3	19.3		
9	29.9	29,6	29.3	30.8	28.7	25.4	21.8	18.4	14	
10	23.4	23,1	22.9	24.3	25.3	23.6	20,6	17.5	13,4	
12		15.2	15	16.3	17.2	17.8	18,3	15.7	11,6	
14		10,4	10.3	11,5	12,4	13	13,4	13.8	11,	
16			7.1	8.3	9.1	9.7	10.2	10.5	10.	
18			4.8	6.0	6.8	7.4	8	8.2	8,5	
20				4.3	5.1	5.6	6.2	6.4	6.7	
22				2.9	3.7	4.3	4.9	5.0	5.3	
24			HAR		2,6	3.2	3.8	3.9	4.2	
26					1,7	2.3	2.9	3.0	3,3	
28						1,6	2,2	2.3	2.5	
30							1.5	1.7	1.9	
32				A BA				1.1	1.4	
倍率 Parts of line	12	10	8	6	5	4	4	3	2	
最小主臂仰角 (°) Min boom angle	20	22	23	24	25	33	38	42	48	
最大主臂仰角 (°) Max,boom angle	71	77	77	78	80	81	81	81	81	
使用吊钩 hook block		吊钩(10 block for 1				50 吨吊针 hook bloo	均(418kg) k for 50t			

表 3-3table3-3

单位· 吨 Unit·t

		19.2t	平衡重	全曲:	大服 36	O° 作v		1立: 地	Unit
19	2t cour		ht 360°			extend-		agers	
幅度 Working			‡ 1	臂长度(om lengt	Carlo	33	HALLEY
radius (m)	12.8	17,2	21.6	26	30,4	34.8	39,2	43.6	48
3	100	80	Ma	J. 100			402 3	(IECON)	I ST THE
4	88	70	61						
5	70	61	54.3	42	40		E I		
6	57	54	48.7	42	36.5	31,1			
7	47	47.5	44.1	38,6	33,5	29	24.5		III S
8	40.5	40	40.2	35,3	31,1	27.2	23,3	19,3	
9	34.5	35	35	32,3	28.7	25.4	21.8	18,4	14
10	30	30	30	29,9	26,6	23,6	20.6	17.5	13,4
12		23	22,8	24.1	23.3	20.9	18.5	15.7	11.6
14		16,6	16,4	17.7	18,6	18.5	16.4	14.2	11.3
16			12.2	13.4	14.2	14.9	14.9	13	10.1
18			9,2	10.4	11.2	11.8	12.3	11.6	9 2
20				8.1	8.9	9.5	10	10.2	8.3
22				6.3	7,1	7.7	8,2	8.4	7.7
24					5.7	6.2	6.8	7.0	7,1
26					4.5	5.1	5.7	5.8	6 1
28	186		7 10 200	The Tol	10 10 10	4.6	4.7	4.8	5.1
30						3,3	3.9	4.0	4.2
32		1000		The state of			3.2	3.3	3 5
34							2.5	2.7	2 9
36	A STATE OF THE PARTY OF THE PAR			LINE N	Visit III		His way	2.1	2.4
38								1,6	1.9
39								THE REAL PROPERTY.	1.5
40									1,1
42		CORR D			EDES.	Relia H	1000000	3-20	
倍率 Parts of line	12	10	8	6	5	4	4	3	2
最小主臂仰角 (°°) Min boom angle	20	22	23	24	25	25	26	26	26
最大主臂仰角 (°) Max.boom angle	71	77	77	78	80	81	81	81	81
使用吊钩 hook block		吨吊钩(10 k block for				0 吨吊钩(hook block			

表 3-4table3-4

QY100K TRUCK CRANE TECHNICAL SPECIFICATION

QY100K 汽车起重机副臂起重性能表

QY100K Truck Crane Total Rated Lifting Load for Jib

单位: 吨 Unit:t

	48m 主臂 boom length 48m												
主臂仰角 boom angle		10.6m 副臂 jib length 10.6m							8.1m 副臂 ji	b length 18	3,1m		
	副臂 0°	jib0°	副臂 15° jib15°		副臂 30°	jib30°	副臂 0°	副臂 0° jib0°		jib15°	副臂 30° jib30		
	起重量 Lifting capacity	幅度(m) Working radius	起重量 Lifting capacity	幅度(m) Working radius	起重量 Lifting capacity	幅度(m) Working radius	起重量 Lifting capacity	幅度(m) Working radius	起重量 Lifting capacity	幅度(m) Working radius	起重量 Lifting capacity	幅度(m) Working radiu	
78°	7	13.3	5	15.7	3.5	17.9	3.6	15.3	2.7	19,5	2.1	23.2	
75°	6,5	16.3	4.3	18.7	3.4	20,7	3,3	18.6	2.5	22.7	2.0	26.3	
72°	6.0	19.2	4.0	21.5	3.3	23.5	3.1	21.9	2.4	25.9	1.9	29.3	
70°	5.2	21.1	3.8	23,4	3,2	25,3	2.9	24	2.3	28	1.8	31,3	
65°	4.4	25.7	3.6	27.9	3.1	29.7	2.7	29.2	2.2	33	1.7	36	
60°	2.8	30.1	2.5	32.2	2.4	33,8	2	34.2	1.7	37.7	1,5	40,5	
55°	1.6	34.3	1.5	36.2	1.4	37.7	1.1	38.8	0.9	42.1	0.8	44.5	
50°	0.8	38.1	0.8	39.9	0.7	41.2	imm			mimi.	ITIE.	on miles	
吊钩重量 Weight of hook block							25kg						

表 4-1 table 4-1

单位: 吨 Unit:t

	,0: —	14,3t 平衡重 全伸支腿 侧、后方作业 14,3t counterweight,on full-extended outriggers,boom over side or rear 48m 主臂 boom length 48m												
主臂仰角 boom angle		10.	6m 副臂 jib	length 10,6		Join length -	NAME OF TAXABLE PARTY.	8.1m 副臂 j	ib length 18	3,1m				
	副臂 0° jib0°		副臂 15°	jib15°	副臂 30°	jib30°	副臂 0°	jib0°	副臂 15°	jib15°	副臂 30°	jib30°		
	起重量 Lifting capacity	幅度(m) Working radius	起重量 Lifting capacity	幅度(m) Working radius	起重量 Lifting capacity	幅度(m) Working radius	起重量 Lifting capacity	幅度(m) Working radius	起重量 Lifting capacity	幅度(m) Working radius	起重量 Lifting capacity	幅度(m) Working radius		
78°	7	13.3	5	15.7	3.5	17.9	3.6	15,3	2.7	19.5	2,1	23,2		
75°	6.5	16.3	4.3	18.7	3.4	20.7	3.3	18.6	2.5	22.7	2.0	26.3		
72°	6.0	19.2	4.0	21.5	3.3	23,5	3.1	21.9	2.4	25.9	1.9	29.3		
70°	5.2	21.1	3.8	23.4	3.2	25.3	2.9	24	2.3	28	1.8	31.3		
65°	4.5	25.7	3.6	27.9	3.1	29.7	2.7	29.2	2.2	33	1.7	36		
60°	4	30,1	3.4	32.2	3	33.8	2.5	34.2	2	37.7	1.6	40.5		
55°	2.7	34.3	2.5	36.2	2.3	37.7	1.9	38,9	1.7	42.2	1.5	44.5		
50°	1.7	38,1	1.6	39.9	1.6	41.2	1.2	43.2	1	46.2	1	48.3		
45°	1,1	41.7	1	43.3	1	44.4								
吊钩重量 Weight of hook block						22	25kg							

表 4-2table4-2

角位、陆 Unitet

		48m 主臂 boom length 48m												
主臂仰角 boom angle		10.	6m 副臂 jib	length 10,6	îm		1	8.1m 副臂 j	ib length 18	3,1m				
	副臂 0° jib0°		副臂 15°	jib15°	副臂 30°	jib30°	副臂 0°	jib0°	副臂 15°	jib15°	副臂 30°			
	起重量 Lifting capacity	幅度(m) Working radius												
78°	7	13.3	5	15.7	3,5	17.9	3,6	15.3	2.7	19,5	2.1	23.2		
75°	6.5	16.3	4.3	18.7	3.4	20.7	3.3	18.6	2,5	22.7	2.0	26.3		
72°	6.0	19.2	4.0	21.5	3.3	23,5	3.1	21.9	2.4	25.9	1.9	29.3		
70°	5.2	21.1	3.8	23.4	3.2	25.3	2.9	24	2.3	28	1.8	31.3		
65°	4.5	25.7	3.6	27.9	3.1	29.7	2.7	29.2	2.2	33	1.7	36		
60°	4.1	30.1	3.4	32.2	3.0	33.8	2.5	34.2	2	37.7	1.6	40.5		
55°	3.5	34.3	3.2	36.2	2.9	37.7	2.3	38.9	1.9	42.2	1,5	44.6		
50°	2.5	38.1	2.3	39.9	2.2	41.2	1.8	43.2	1.6	46.2	1.4	48.3		
45°	1.8	41.7	1.7	43.3	1.6	44.4	1.2	47.2	1.1	50	1	51,6		
40°	1,2	44.9	1,1	46.4	1,0	47.3	(-)-					mm.		

表 4-3table4-3

表 3、表 4 的说明:

- ※ 表中所列起重量是在平整坚固的地面上本机所能保证的最大起重量,严禁超过该起重量作业;
- ※ 表中所列额定起重量包括吊钩和吊具的重量;
- ※ 表中的工作幅度是包括吊臂的变形量在内的实际值;
- ※ 臂端单滑轮的起重性能同 10.6 米副臂 0° 安装角时的起重性能 (按主臂仰角);
- ※ 除全伸支腿基本臂工况外,即使空载,也不要使吊臂的仰角处于以上各工况表中所给出的范围以外,以防起重机倾覆;
- ※ 允许起重机在不大于7级风的情况下作业。

Notes on Table 3 and Table 4:

- **The data shown in the tables are the max_lifting capacity when the crane is set up on level and firm ground,

 **The total rated lifting capacity includes the weight of hook block and slings.

 **The working radius in tables is the actual value including boom deflection under loads.

 **Lifting capacity for single, sheave on boom tip is the same as that for jib of 10.6m with offset angle of 0°.

 **Except under the condition of base boom with full—extended outriggers, even no load, never operate the vehicle beyond the values listed in the tables to prevent crane tipping.
- the tables to prevent crane tipping, ** Lifting operation is still permissible under the condition of less than force 7 wind.



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完善计量效置体系合格证书



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